# ON ESTIMATION IN THREE AND FOUR PHASE SAMPLING 

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ABSTRACT: Multiphase sampling has been widely used in literature when information about sampling frame is not available. In this short note it is shown that the estimation in multiphase sampling can only be based upon two phases. The result has been proved for three and four phases only.

Key Words: Auxiliary Information, Three and Four Phase Sampling.

## 1. INTRODUCTION

Often it happened that the information about sampling frame in a finite population setup is not available and the conventional sampling methods are no more useful. The multiphase sampling is a popular rescue source in these sorts of situations. To set up the seen suppose that it is known in advance that a finite population has $N$ differentiable units but the complete listing of these population units is not available and hence the popular designs like simple random sampling, stratified random sampling and others are not applicable. The multiphase sampling design is perhaps the most powerful design that can be efficiently used in situations where sampling frame is not available.
The notations of multiphase sampling are bit different from the conventional single phase sampling in that sample of different sizes are selected in phases and at each phase information is collected about some auxiliary variables that are thought to increase the efficiency of estimation of variable of interest. The information from main variable of interest is collected at the last phase only. We now provide the main theme of multiphase sampling by describing some of the common notations. Let $n_{j} ; j=1,2, \ldots, p$; be the size of sample drawn from a population of size $N$ at $j$-th phase, $\bar{x}_{j} ; j=1,2, \ldots, p$; be the mean of an auxiliary variable based upon the sample at $j$-th phase; that is $\bar{x}_{j}=n_{j}^{-1} \sum_{i=1}^{n_{j}} x_{i j}$ and $\bar{y}_{p}$ be the mean of main variable of interest based upon the last phase sample. Some other notations are described below:

$$
\left.\begin{array}{l}
\theta_{j}=1 / n_{j}-1 / N ; \bar{x}_{j}=\bar{X}+\bar{e}_{x_{j}}, j=1,2, \ldots, p ; \\
\bar{y}_{q}=\bar{Y}+\bar{e}_{y_{q}} ; E\left(\bar{e}_{y_{q}}^{2}\right)=\theta_{j} S_{y}^{2} ; E\left(\bar{e}_{x_{j}}^{2}\right)=\theta_{j} S_{x}^{2} ; \\
E\left(\bar{e}_{y_{q}} \bar{e}_{x_{j}}\right)=\theta_{j} S_{x y} ;  \tag{1.1}\\
E\left(\bar{e}_{x_{h}}-\bar{e}_{x_{j}}\right)^{2}=\left(\theta_{j}-\theta_{h}\right) S_{x}^{2} ; h<j
\end{array}\right\}
$$

where $\theta_{j}$ is sampling fraction at $j$ th phase, $\bar{x}_{j}$ is sample mean of auxiliary variable at $j$ th phase, $S_{x}^{2}$ is population variance of auxiliary variable, $S_{y}^{2}$ is variance of study variable and $S_{x y}$ is covariance between $X$ and $Y$. We follow the description given in [1] and [2] about the quantities $\bar{e}_{y}$ and $\bar{e}_{x_{j}}$ and assume that these quantities are very small. Several estimators have been proposed for use with two phase sampling only. Following estimator was proposed by [2] in two phase sampling using two auxiliary variables:
$t_{1}=\left[\bar{y}_{2}+b_{y x}\left(\bar{x}_{1}-\bar{x}_{2}\right)\right] \frac{\bar{z}_{1}}{\bar{z}_{2}}$
where $b_{y x}$ is regression coefficient between $X$ and $Y$. A regression-in-ratio estimator was also proposed by [2] as under:
$t_{2}=\left[\bar{y}_{2}+b_{y z}\left(\bar{z}_{1}-\bar{z}_{2}\right)\right] \frac{\bar{X}}{\bar{x}_{2}}$
where $b_{y z}$ is regression coefficient between $Y$ and $Z$. A chain-ratio type estimators proposed by [3] is are given as:
$t_{3}=y_{2} \frac{\bar{z}_{1}}{\bar{z}_{2}} \cdot \frac{\bar{X}}{\bar{x}_{1}}$ and $t_{4}=y_{2} \frac{\bar{z}_{2}}{\bar{z}_{1}} \cdot \frac{\bar{x}_{1}}{\bar{X}}$
Three estimators are proposed by [4,5] for use in two phase sampling. These estimators are ratio-in-regression and regression-in-ratio type estimators. The first estimator proposed by [4] is a regression-in-ratio type estimator and is given as:

$$
\begin{equation*}
t_{5}=\frac{\bar{y}_{2}}{\bar{z}_{2}}\left[\bar{z}_{1}+b_{z x}\left(\bar{X}-\bar{x}_{1}\right)\right] \tag{1.5}
\end{equation*}
$$

Another estimator proposed by [5] is a ratio-in-regression and is given as:
$t_{6}=\bar{y}_{2}+b_{y z}\left(\frac{\bar{z}_{1}}{\bar{x}_{1}} \bar{X}-\bar{z}_{2}\right)$
A third estimator proposed by [5] is a regression-inregression type estimator and is given as:
$t_{7}=\bar{y}_{2}+b_{y z}\left\{\left(\bar{z}_{1}-\bar{z}_{2}\right)-b_{z x}\left(\bar{x}_{1}-\bar{X}\right)\right\}$
Several other estimators have been proposed in literature. Some other notable references are of [6], [7, 8], [9] and many others.

## 2. MAIN RESULTS

In this section we have given some main results for estimation in multiphase sampling. These results are given for three and four phase sampling only. Different estimators are given for three phase sampling.

## a. THREE PHASE SAMPLING

In this section the result for three phase sampling has been given. We start with the very simple formation and define the following estimator:

$$
\begin{equation*}
\bar{y}_{3(1)}^{\prime}=\bar{y}_{3}+\beta_{1}\left(\bar{x}_{1}-\bar{x}_{2}\right)+\beta_{2}\left(\bar{x}_{2}-\bar{x}_{3}\right) \tag{2.1}
\end{equation*}
$$

where $\beta_{1}$ and $\beta_{2}$ are unknown quantities which minimize the variance of (2.1). Using the notations given in (1.1) the above estimator can be written as:

$$
\begin{aligned}
& \bar{y}_{3(1)}^{\prime}=\bar{Y}+\bar{e}_{y_{3}}+\beta_{1}\left(\bar{e}_{x_{1}}-\bar{e}_{x_{2}}\right)+\beta_{2}\left(\bar{e}_{x_{2}}-\bar{e}_{x_{3}}\right) \\
& \bar{y}_{3(1)}^{\prime}-\bar{Y}=\bar{e}_{y_{3}}+\beta_{1}\left(\bar{e}_{x_{1}}-\bar{e}_{x_{2}}\right)+\beta_{2}\left(\bar{e}_{x_{2}}-\bar{e}_{x_{3}}\right)
\end{aligned}
$$

Squaring and applying the expectation, we get; on use of (1.1); the Mean Square Error of (2.1) as:

$$
\begin{align*}
S= & \operatorname{MSE}\left(\bar{y}_{3(1)}^{\prime}\right)=E\left(\bar{y}_{3(1)}^{\prime}-\bar{Y}\right)^{2} \\
= & \theta_{3} S_{y}^{2}+\left(\theta_{2}-\theta_{1}\right) \beta_{1}^{2} S_{x}^{2}+\left(\theta_{3}-\theta_{2}\right) \beta_{1}^{2} S_{x}^{2}  \tag{2.2}\\
& -2\left(\theta_{2}-\theta_{1}\right) \beta_{1} S_{x y}-2\left(\theta_{3}-\theta_{2}\right) \beta_{2} S_{x y}
\end{align*}
$$

To obtain the optimum values of $\beta_{1}$ and $\beta_{2}$ that minimizes " $S$ ", we partially differentiate (2.2) with respect to $\beta_{1}$ and $\beta_{2}$ to get:

$$
\begin{equation*}
\frac{\partial S}{\partial \beta_{1}}=2\left(\theta_{2}-\theta_{1}\right) \beta_{1} S_{x}^{2}-2\left(\theta_{2}-\theta_{1}\right) S_{x y} \tag{2.3}
\end{equation*}
$$

and
$\frac{\partial S}{\partial \beta_{2}}=2\left(\theta_{3}-\theta_{2}\right) \beta_{2} S_{x}^{2}-2\left(\theta_{3}-\theta_{2}\right) S_{x y}$
Equating (2.3) and (2.4) to zero and solving we have:
$\beta_{1}=\beta_{2}=S_{x y} / S_{x}^{2}=\rho_{x y} S_{y} / S_{x}$
Using (2.5) in (2.1) and (2.2) the estimator and its mean square error become:

$$
\begin{equation*}
\bar{y}_{3(1)}^{\prime}=\bar{y}_{3}+\beta\left(\bar{x}_{1}-\bar{x}_{3}\right) \tag{2.6}
\end{equation*}
$$

with
$\operatorname{MSE}\left(\bar{y}_{3(1)}^{\prime}\right)=\theta_{3} S_{y}^{2}\left(1-\rho^{2}\right)+\theta_{1} \rho^{2} S_{y}^{2}$
Now let's consider another formation of the estimator in three phase sampling:

$$
\begin{equation*}
\bar{y}_{3(2)}^{\prime}=\bar{y}_{3}+\beta_{1}\left(\bar{x}_{1}-\bar{x}_{3}\right)+\beta_{2}\left(\bar{x}_{2}-\bar{x}_{3}\right) \tag{2.8}
\end{equation*}
$$

Using notations given in (1.1) in (2.8) we have:

$$
\begin{aligned}
& \bar{y}_{3(2)}^{\prime}=\bar{Y}+\bar{e}_{y_{3}}+\beta_{1}\left(\bar{e}_{x_{1}}-\bar{e}_{x_{3}}\right)+\beta_{2}\left(\bar{e}_{x_{2}}-\bar{e}_{x_{3}}\right) \\
& \bar{y}_{3(2)}^{\prime}-\bar{Y}=\bar{e}_{y_{3}}+\beta_{1}\left(\bar{e}_{x_{1}}-\bar{e}_{x_{3}}\right)+\beta_{2}\left(\bar{e}_{x_{2}}-\bar{e}_{x_{3}}\right)
\end{aligned}
$$

Squaring and applying expectations, the mean square error of (2.8) is given as:

$$
\begin{align*}
S= & \operatorname{MSE}\left(\bar{y}_{3(2)}^{\prime}\right)=E\left(\bar{y}_{3(2)}^{\prime}-\bar{Y}\right)^{2} \\
& =\theta_{3} S_{y}^{2}+\left(\theta_{3}-\theta_{1}\right) \beta_{1}^{2} S_{x}^{2}+\left(\theta_{3}-\theta_{2}\right) \beta_{2}^{2} S_{x}^{2}  \tag{2.9}\\
& -2\left(\theta_{3}-\theta_{1}\right) \beta_{1} S_{x y}-2\left(\theta_{3}-\theta_{2}\right) \beta_{2} S_{x y} \\
& +2\left(\theta_{3}-\theta_{2}\right) \beta_{1} \beta_{2} S_{x}^{2}
\end{align*}
$$

Differentiating (2.9) with respect to $\beta_{1}$ and $\beta_{2}$ and equating the resulting derivatives to zero we have:
$2\left(\theta_{3}-\theta_{1}\right) \beta_{1} S_{x}^{2}-2\left(\theta_{3}-\theta_{1}\right) S_{x y}+2\left(\theta_{3}-\theta_{2}\right) \beta_{2} S_{x}^{2}=0$
(2.10)
and $2\left(\theta_{3}-\theta_{2}\right) \beta_{2} S_{x}^{2}-2\left(\theta_{3}-\theta_{2}\right) S_{x y}+2\left(\theta_{3}-\theta_{2}\right) \beta_{1} S_{x}^{2}=0$

From (2.11) we have:
$\beta_{1}+\beta_{2}=S_{x y} / S_{x}^{2}$ or $\quad \beta_{2}=S_{x y} / S_{x}^{2}-\beta_{1}$

Using (2.12) in (2.10) we have:
$2\left(\theta_{3}-\theta_{1}\right) \beta_{1} S_{x}^{2}-2\left(\theta_{3}-\theta_{1}\right) S_{x y}$
$+2\left(\theta_{3}-\theta_{2}\right)\left(\frac{S_{x y}}{S_{x}^{2}}-\beta_{1}\right) S_{x}^{2}=0$
On simplification we have $\beta_{1}=S_{x y} / S_{x}^{2}$ and hence from (2.12) we have $\beta_{2}=0$. Using these values of $\beta_{1}$ and $\beta_{2}$ in (2.8) and (2.9) the estimator and the mean square error turned out to be:

$$
\begin{equation*}
\bar{y}_{3(2)}^{\prime}=\bar{y}_{3}+\beta\left(\bar{x}_{1}-\bar{x}_{3}\right) \tag{2.13}
\end{equation*}
$$

with
$\operatorname{MSE}\left(\bar{y}_{3(2)}^{\prime}\right)=\theta_{3} S_{y}^{2}\left(1-\rho^{2}\right)+\theta_{1} \rho^{2} S_{y}^{2}$
The estimator given in (2.13) and (2.14) are same as given in (2.6) and (2.7).

We now give another formation of the estimator following the idea of Kiregyera (1984) as under:

$$
\begin{equation*}
\bar{y}_{3(3)}^{\prime}=\bar{y}_{3}+\beta_{1}\left[\left(\bar{x}_{1}-\bar{x}_{3}\right)+\beta_{2}\left(\bar{x}_{2}-\bar{x}_{3}\right)\right] \tag{2.15}
\end{equation*}
$$

Using the notations given in (1.1) the estimator (2.15) can be written as:

$$
\begin{aligned}
& \bar{y}_{3(3)}^{\prime}=\bar{Y}+\bar{e}_{y_{3}}+\beta_{1}\left(\bar{e}_{x_{1}}-\bar{e}_{x_{3}}\right)+\beta_{1} \beta_{2}\left(\bar{e}_{x_{2}}-\bar{e}_{x_{3}}\right) \\
& \bar{y}_{3(3)}^{\prime}-\bar{Y}=\bar{e}_{y_{3}}+\beta_{1}\left(\bar{e}_{x_{1}}-\bar{e}_{x_{3}}\right)+\beta_{1} \beta_{2}\left(\bar{e}_{x_{2}}-\bar{e}_{x_{3}}\right)
\end{aligned}
$$

Squaring and applying expectations, the mean square error of (2.8) is given as:

$$
\begin{align*}
S= & \operatorname{MSE}\left(\bar{y}_{3(3)}^{\prime}\right)=E\left(\bar{y}_{3(3)}^{\prime}-\bar{Y}\right)^{2}=\theta_{3} S_{y}^{2}+\left(\theta_{3}-\theta_{1}\right) \beta_{1}^{2} S_{x}^{2} \\
& +\left(\theta_{3}-\theta_{2}\right) \beta_{1}^{2} \beta_{2}^{2} S_{x}^{2}-2\left(\theta_{3}-\theta_{1}\right) \beta_{1} S_{x y} \\
& -2\left(\theta_{3}-\theta_{2}\right) \beta_{1} \beta_{2} S_{x y}+2\left(\theta_{3}-\theta_{2}\right) \beta_{1}^{2} \beta_{2} S_{x}^{2} \tag{2.16}
\end{align*}
$$

Differentiating (2.16) with respect to $\beta_{1}$ and $\beta_{2}$ and equating the resulting derivatives to zero we have:

$$
\begin{aligned}
& 2\left(\theta_{3}-\theta_{1}\right) \beta_{1} S_{x}^{2}+2\left(\theta_{3}-\theta_{2}\right) \beta_{1} \beta_{2}^{2} S_{x}^{2}-2\left(\theta_{3}-\theta_{1}\right) S_{x y} \\
& -2\left(\theta_{3}-\theta_{2}\right) \beta_{2} S_{x y}+4\left(\theta_{3}-\theta_{2}\right) \beta_{1} \beta_{2} S_{x}^{2}=0
\end{aligned}
$$

$$
\begin{align*}
& 2\left(\theta_{3}-\theta_{2}\right) \beta_{1}^{2} \beta_{2} S_{x}^{2}-2\left(\theta_{3}-\theta_{2}\right) \beta_{1} S_{x y}  \tag{2.18}\\
& +2\left(\theta_{3}-\theta_{2}\right) \beta_{1}^{2} S_{x}^{2}=0
\end{align*}
$$

From (2.18) we have $\beta_{2}=S_{x y} /\left(\beta_{1} S_{x}^{2}\right)-1$. Using this value of $\beta_{2}$ in (2.17) we have:

$$
\begin{aligned}
& 2\left(\theta_{3}-\theta_{1}\right) \beta_{1} S_{x}^{2}+2\left(\theta_{3}-\theta_{2}\right) \beta_{1}\left(\frac{S_{x y}}{\beta_{1} S_{x}^{2}}-1\right)^{2} S_{x}^{2} \\
& -2\left(\theta_{3}-\theta_{1}\right) S_{x y}-2\left(\theta_{3}-\theta_{2}\right)\left(\frac{S_{x y}}{\beta_{1} S_{x}^{2}}-1\right) S_{x y} \\
& +4\left(\theta_{3}-\theta_{2}\right) \beta_{1}\left(\frac{S_{x y}}{\beta_{1} S_{x}^{2}}-1\right) S_{x}^{2}=0
\end{aligned}
$$

After some algebra we have $\beta_{1}=S_{x y} / S_{x}^{2}$ and hence $\beta_{2}=0$. So using these values of $\beta_{1}$ and $\beta_{2}$ in (2.15) and (2.16) the estimator and its mean square error are same as given in (2.13) and (2.14) and hence we conclude that the simple estimator of population mean in three phase sampling is given as in (2.6) with mean square error as given in (2.7).

## b. FOUR PHASE SAMPLING

In this section we have given some result about estimation in four phase sampling. Again we start as before and give a very simple estimator as:

$$
\begin{equation*}
\bar{y}_{4(1)}^{\prime}=\bar{y}_{4}+\beta_{1}\left(\bar{x}_{1}-\bar{x}_{2}\right)+\beta_{2}\left(\bar{x}_{2}-\bar{x}_{3}\right)+\beta_{3}\left(\bar{x}_{3}-\bar{x}_{4}\right) \tag{2.19}
\end{equation*}
$$

Arguing as before and using (1.1) in (2.19) we have:

$$
\begin{aligned}
\bar{y}_{4(1)}^{\prime}-\bar{Y}= & \bar{e}_{y_{4}}+\beta_{1}\left(\bar{e}_{x_{1}}-\bar{e}_{x_{2}}\right)+\beta_{2}\left(\bar{e}_{x_{2}}-\bar{e}_{x_{3}}\right) \\
& +\beta_{3}\left(\bar{e}_{x_{3}}-\bar{e}_{x_{4}}\right)
\end{aligned}
$$

Squaring and applying expectation, the mean square error of (2.19) is given as:

$$
\begin{align*}
S=M S E & \left(\bar{y}_{4(1)}^{\prime}\right)=\theta_{3} S_{y}^{2}+\left(\theta_{2}-\theta_{1}\right) \beta_{1}^{2} S_{x}^{2}+\left(\theta_{3}-\theta_{2}\right) \beta_{2}^{2} S_{x}^{2} \\
& +\left(\theta_{4}-\theta_{3}\right) \beta_{3}^{2} S_{x}^{2}-2\left(\theta_{2}-\theta_{1}\right) \beta_{1} S_{x y} \\
& -2\left(\theta_{3}-\theta_{2}\right) \beta_{2} S_{x y}-2\left(\theta_{4}-\theta_{3}\right) \beta_{3} S_{x y} \tag{2.20}
\end{align*}
$$

Differentiating (2.20) with respect to $\beta_{1}, \beta_{2}$ and $\beta_{3}$ and equating the resulting derivatives to zero we have:

$$
\begin{aligned}
& 2\left(\theta_{2}-\theta_{1}\right) \beta_{1} S_{x}^{2}-2\left(\theta_{2}-\theta_{1}\right) S_{x y}=0 \\
& 2\left(\theta_{3}-\theta_{2}\right) \beta_{2} S_{x}^{2}-2\left(\theta_{3}-\theta_{2}\right) S_{x y}=0 \\
& 2\left(\theta_{4}-\theta_{3}\right) \beta_{3} S_{x}^{2}-2\left(\theta_{4}-\theta_{3}\right) S_{x y}=0
\end{aligned}
$$

Solving above equations we have:
$\beta_{1}=\beta_{2}=\beta_{3}=S_{x y} / S_{x}^{2}=\rho_{x y} S_{y} / S_{x}$
Using (2.21) in (2.19) and (2.20), the estimator of population mean along with its mean square error in four phase sampling is given as:
$\bar{y}_{4(1)}^{\prime}=\bar{y}_{4}+\beta\left(\bar{x}_{1}-\bar{x}_{4}\right)$
with
$\operatorname{MSE}\left(\bar{y}_{4(1)}^{\prime}\right)=\theta_{4} S_{y}^{2}\left(1-\rho^{2}\right)+\theta_{1} \rho^{2} S_{y}^{2}$
Now we consider following formation of the estimator:
$\bar{y}_{4(2)}^{\prime}=\bar{y}_{4}+\beta_{1}\left(\bar{x}_{1}-\bar{x}_{4}\right)+\beta_{2}\left(\bar{x}_{2}-\bar{x}_{4}\right)+\beta_{3}\left(\bar{x}_{3}-\bar{x}_{4}\right)$
Using (1.1) in (2.24) we have:
$\bar{y}_{4(2)}^{\prime}-\bar{Y}=\bar{e}_{y_{4}}+\beta_{1}\left(\bar{e}_{x_{1}}-\bar{e}_{x_{4}}\right)+\beta_{2}\left(\bar{e}_{x_{2}}-\bar{e}_{x_{4}}\right)+\beta_{3}\left(\bar{e}_{x_{3}}-\bar{e}_{x_{4}}\right)$
Squaring and applying expectation we have:

$$
\begin{align*}
S=M S E & \left(\bar{y}_{4(2)}^{\prime}\right)=E\left(\bar{y}_{4(2)}^{\prime}-\bar{Y}\right)^{2}=\theta_{4} S_{y}^{2}+\left(\theta_{4}-\theta_{1}\right) \beta_{1}^{2} S_{x}^{2} \\
& +\left(\theta_{4}-\theta_{2}\right) \beta_{2}^{2} S_{x}^{2}+\left(\theta_{4}-\theta_{3}\right) \beta_{3}^{2} S_{x}^{2} \\
& -2\left(\theta_{4}-\theta_{1}\right) \beta_{1} S_{x y}-2\left(\theta_{4}-\theta_{2}\right) \beta_{2} S_{x y} \\
& -2\left(\theta_{4}-\theta_{3}\right) \beta_{3} S_{x y}+2\left(\theta_{4}-\theta_{2}\right) \beta_{1} \beta_{2} S_{x}^{2} \\
& +2\left(\theta_{4}-\theta_{3}\right) \beta_{1} \beta_{3} S_{x}^{2}+2\left(\theta_{4}-\theta_{3}\right) \beta_{2} \beta_{3} S_{x}^{2} \tag{2.25}
\end{align*}
$$

Differentiating (2.25) with respect to $\beta_{1}, \beta_{2}$ and $\beta_{3}$ and equating the resulting derivatives to zero we have:
$2\left(\theta_{4}-\theta_{1}\right) \beta_{1} S_{x}^{2}+2\left(\theta_{4}-\theta_{2}\right) \beta_{2} S_{x}^{2}$
$+2\left(\theta_{4}-\theta_{3}\right) \beta_{3} S_{x}^{2}=2\left(\theta_{4}-\theta_{1}\right) S_{x y}$
$2\left(\theta_{4}-\theta_{2}\right) \beta_{1} S_{x}^{2}+2\left(\theta_{4}-\theta_{2}\right) \beta_{2} S_{x}^{2}$
$+2\left(\theta_{4}-\theta_{3}\right) \beta_{3} S_{x}^{2}=2\left(\theta_{4}-\theta_{2}\right) S_{x y}$
$2\left(\theta_{4}-\theta_{3}\right) \beta_{1} S_{x}^{2}+2\left(\theta_{4}-\theta_{3}\right) \beta_{2} S_{x}^{2}$
$+2\left(\theta_{4}-\theta_{3}\right) \beta_{3} S_{x}^{2}=2\left(\theta_{4}-\theta_{3}\right) S_{x y}$
Solving above three equations simultaneously we have
$\beta_{1}=S_{x y} / S_{x}^{2}, \beta_{2}=0$ and $\beta_{3}=0$. Using these values in (2.19) the four phase sampling estimator (2.24) becomes

$$
\begin{equation*}
\bar{y}_{4(2)}^{\prime}=\bar{y}_{4}+\beta_{1}\left(\bar{x}_{1}-\bar{x}_{4}\right) . \tag{2.26}
\end{equation*}
$$

Further, by using the optimum values of $\beta_{1}, \beta_{2}$ and $\beta_{3}$ in (2.25), the mean square error of (2.26) is
$\operatorname{MSE}\left(\bar{y}_{4(1)}^{\prime}\right)=\theta_{4} S_{y}^{2}\left(1-\rho^{2}\right)+\theta_{1} \rho^{2} S_{y}^{2}$.
which again depends upon information of first and last phase only.
3. EMPIRICAL STUDY

In this section we have given a brief empirical study by using an artificial data. Some summary measures for the data are given below
$N=46, \bar{X}=38.4, \bar{Y}=61.5$
$S_{x}^{2}=79.5, S_{y}^{2}=297.1$
$S_{x y}=-120.9, \rho_{x y}=-0.79$
The following table shows the variance of three phase sampling estimator for various sample sizes at various phases.

|  | Phase $\mathbf{1}$ |  |
| :--- | :---: | :---: |
| Phase 3 | $\boldsymbol{n}_{\boldsymbol{l}}=\mathbf{2 0}$ | $\boldsymbol{n}_{\boldsymbol{l}}=\mathbf{3 0}$ |
| $\boldsymbol{n}_{\mathbf{3}}=\mathbf{4}$ | 70.972 | 69.111 |
| $\boldsymbol{n}_{\mathbf{3}}=\mathbf{8}$ | 33.835 | 31.974 |
| $\boldsymbol{n}_{\mathbf{3}}=\mathbf{1 2}$ | 21.456 | 19.594 |
| $\boldsymbol{n}_{\mathbf{3}}=\mathbf{1 6}$ | 15.266 | 13.405 |
|  | Phase $\mathbf{1}$ |  |
|  | $\boldsymbol{n}_{\boldsymbol{l}}=\mathbf{2 0}$ | $\boldsymbol{n}_{\boldsymbol{l}}=\mathbf{3 0}$ |
| $\boldsymbol{n}_{\mathbf{4}}=\mathbf{3}$ | 95.731 | 93.869 |
| $\boldsymbol{n}_{\mathbf{4}}=\mathbf{5}$ | 56.117 | 54.256 |
| $\boldsymbol{n}_{\mathbf{4}}=\mathbf{7}$ | 39.140 | 37.279 |
| $\boldsymbol{n}_{\mathbf{4}}=\mathbf{1 0}$ | 26.407 | 24.546 |

We can see that as the phases increase the mean square error starts increasing as should be the case.

## 4. CONCLUSION

In this short note we have shown that the classical regression estimators in multiphase sampling depends only upon information of first and last phase. The information gathered at other phases do not contribute at all in regression type estimation in multiphase sampling.

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